#### ATTiny85 Arcade workshop Kristof Van Beeck - Dries Hulens







### Overview of today

- 09:00 Introduction
- 09:30 PCB Design intro
- 09:45 PCB Soldering & electrical testing
- 10:45 PCB Test & bootloader
- 11:00 SW intro (OLED, I2C, ADCs, Interrupts)
- 12:00 Lunch break
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- 13:30 Develop simple game (Snake)
- 15:30 Download finished games
- 16:00 End

Hardware

- Software



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• Build a mini hand-held battery power arcade game console from scratch



- ATTiny85 controller (8K Bytes memory) 16 MHz
- OLED screen
- 5 push buttons (full D-pad + action button)
- On/off slide switch
- Piezo buzzer for sound effects
- CR2032 battery
- Through-hole PCB







• Credits!

Original implementation from <u>Electronoobs</u> D-pad upgrade & most games from <u>Daniel C.</u> Some games created by <u>Andy Jackson</u>



- We'll go over entire development:
  - Schematic → draw and manufacture PCB → Soldering → Electrical test → SW test → Software implementation of simple game



- PCB Design: EAGLE Layout Editor
- Software is written using Arduino IDE and language



• 17 supported games (one at a time <sup>(iii)</sup>):



# 2) <u>Arkanoid (1986)</u>



#### Excite Bike (1984)



#### Bomberman (1983)



#### Dugger (1988)



Frogger (1981)



#### Space Invaders (1978)



#### Tiny Gilbert (platformer)





• 17 supported games (one at a time <sup>(iii)</sup>):

#### Morpion (tic-tac-toe)



#### Pacman (1980)



#### Pinball (1984)



#### Snake (1976)



#### Pipeline (1978)



#### Plaque Attack (1983)



#### Hat Trick (1988)



#### <u>Tetris (1984)</u>



#### Missile Command (1980)





- 3D printed housing
- Not part of this workshop
- Fusion360 CAD software (free for students!) Prusa MK3 printer







• Location of course files:

https://gitlab.com/EAVISE/workshops/

ATTinyArcadeV2

- Task 1:
  - Download ZIP from course URL
    - Contains these slides, PCB, datasheets, games, SW templates,...
  - Extract to D:\ drive



### Introduction – ATTiny85 microcontroller

ATtiny25/V / ATtiny45/V / ATtiny85/V

#### Summary



NOTE: TSSOP only for ATtiny45/V

#### Features

- High Performance, Low Power AVR<sup>®</sup> 8-Bit Microcontroller
- Advanced RISC Architecture
  - 120 Powerful Instructions Most Single Clock Cycle Execution
  - 32 x 8 General Purpose Working Registers
- Fully Static Operation
- Non-volatile Program and Data Memories
  - 2/4/8K Bytes of In-System Programmable Program Memory Flash
     Endurance: 10,000 Write/Erase Cycles
  - 128/256/512 Bytes In-System Programmable EEPROM
  - Endurance: 100,000 Write/Erase Cycles
  - 128/256/512 Bytes Internal SRAM
- Programming Lock for Self-Programming Flash Program and EEPROM Data Security

#### Peripheral Features

- 8-bit Timer/Counter with Prescaler and Two PWM Channels
- 8-bit High Speed Timer/Counter with Separate Prescaler
  - 2 High Frequency PWM Outputs with Separate Output Compare Registers
  - Programmable Dead Time Generator
- USI Universal Serial Interface with Start Condition Detector
- 10-bit ADC
- 4 Single Ended Channels
- 2 Differential ADC Channel Pairs with Programmable Gain (1x, 20x)
- Temperature Measurement
- Programmable Watchdog Timer with Separate On-chip Oscillator
- On-chip Analog Comparator
- Special Microcontroller Features
  - debugWIRE On-chip Debug System
  - In-System Programmable via SPI Port
  - External and Internal Interrupt Sources
  - Low Power Idle, ADC Noise Reduction, and Power-down Modes
- Enhanced Power-on Reset Circuit
- Programmable Brown-out Detection Circuit
- Internal Calibrated Oscillator
- I/O and Packages
  - Six Programmable I/O Lines
  - 8-pin PDIP, 8-pin SOIC, 20-pad QFN/MLF, and 8-pin TSSOP (only ATtiny45/V)
- Operating Voltage
  - 1.8 5.5V for ATtiny25V/45V/85V
     2.7 5.5V for ATtiny25/45/85
- Speed Grade
  - ATtiny25V/45V/85V: 0 4 MHz @ 1.8 5.5V, 0 10 MHz @ 2.7 5.5V
  - ATtiny25/45/85: 0 10 MHz @ 2.7 5.5V, 0 20 MHz @ 4.5 5.5V
- Industrial Temperature Range
- Low Power Consumption
  - Active Mode:
  - 1 MHz, 1.8V: 300 μA
- Power-down Mode:
  - 0.1 µA at 1.8V



Rev. 2586QS-AVR-08/2013

#### Introduction - schematic





#### Introduction - PCB





- Task 2:
  - Use the datasheets to calculate the battery life of this mini handheld game console!



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## PCB Design intro

- Task 3:
  - Copy folder "ATTinyArcade\_PCB" (under hardware) to: C:\Users\student\Documents\EAGLE\projects\
     If folder does not exist yet, first open Eagle and login
  - Open Eagle from desktop
    - If login is required:

"elektronicaworkshop@gmail.com"

pwd: "arduinoide1"

• Open project (both schematic and PCB – press F5 if not yet visible)



## PCB Design intro

- Task 4:
  - Add the power LED and resistor to the schematic
  - Position and route both the LED and resistor on the PCB
  - Perform ERC and DRC check
    - <u>https://jlcpcb.com/capabilities/Capabilities</u>
    - → Use the jlcpcb2layer.dru file
  - Use the CAM generator to generate Gerber files
    - → Use the jlcpcb\_2\_layer\_v9.cam file
  - Upload Gerber files to your favorite PCB fab
    - → e.g. <u>https://jlcpcb.com/</u>
  - View PCB preview and check for errors



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## **PCB Soldering**

- PCB for this workshop has been designed completely through hole
  - Solder from lowest components to highest components
  - Do not forget solder jumpers
  - Note polarities and positions of components!
- After soldering we perform an electrical test





### **PCB Soldering**



#### See solder guide here:

https://gitlab.com/EAVISE/workshops/attinyarcadev2/-/blob/main/SOLDER\_GUIDE.md



## **PCB Soldering**

- Move to lab A111
- Hope to finish around 10:45



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- Let's now burn the bootloader (set the fuses) and test the hardware of the board!
- Task 5



- First, install the ATTiny85 libraries
- Start Arduino IDE, go to *File* → *Preferences*

Add an additional board manager URL:

<u>https://raw.githubusercontent.com/damellis/attiny/ide-1.6.x-boards-</u> <u>manager/package\_damellis\_attiny\_index.json</u>

Preferences		×
Settings Network		
Sketchbook location:		
C: Users Kristof Van Beed	k\Documents\Arduino	Browse
Editor language:	System Default v (requires restart of Arduino)	
Editor font size:	13	
Interface scale:	Automatic 100 + % (requires restart of Arduino)	
Theme:	Default theme V (requires restart of Arduino)	
Show verbose output duri	ng: Compilation Upload	
Compiler warnings:	None 🗸	
Display line numbers	Enable Code Folding	
Verify code after uplo	ad 🗌 Use external editor	
Check for updates on	startup Save when verifying or uploading	
Use accessibility featu	res	
Additional Boards Manage	URLs: githubusercontent.com/damellis/attiny/ide-1.6.x-boards-manager/package_damellis_attiny_inde-	dex.jsni
More preferences can be	dited directly in the file	
C: \Users\Kristof Van Beed	\AppData\Local\Arduino15\preferences.txt	
(edit only when A/duino is	not running)	
		OK Cancel

- Tools → Board → Board manager
- Search for attiny, install the board:
  - attiny (by David A. Mellis version 1.0.2)

pe All     titiny by David A. Mellis version 1.0.2 INSTALLED Boards included in this package: ATtiny45, ATtiny85, ATtiny84, ATtiny84. More Info Select version  Install Remove TITINyCore by Spence Konde version 1.5.2 INSTALLED Boards included in this package: Program via ISP or Serialt, ATtiny841/441, ATtiny85/45/25, ATtiny43, ATtiny84/44/24, ATtiny1634, ATtiny828, ATtiny861/461/261, ATtiny167/87, ATtiny88/48, ATtiny4313/2313, USB (Micronucleus) boards:, DigiSpark (t85), Digispark Pro (t167), Watukino Nano (t841), CaliforniaSTEAM (t844), AzduinoUSB (t84, t841, t841, t851, t1634), If Win USB drivers not already installed, run the post_install.bat manually or DL from https://azduino.com/bin/micronucleus. More Info	Boards Manager		
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	megaTinyCore		



:ommunication | Arduino 1.8.13

• Under *Tools* → *Board* → *"Attiny Microcontrollers"* should now be available

Auto Format Ctrl+T   Archive Sketch   commun   Fix Encoding & Reload   EAVIS   Manage Libraries   Ctrl+Shift+I   Serial Monitor   Serial Plotter   ViFi101 / WiFiNINA Firmware Updater	
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Boards "Altiny25/45/85" Boards Manager	
Processor: "ATtiny25" Arduino AVR Boards	
Clock: "Internal 8 MHz" ATtiny Microcontrollers • ATtiny25/45/	5
SSD13 Port ATTinyCore ATtiny24/44/	4
SSD13 Get Board Info custom-avr (in sketchbook) >	
e "fon Burn Bootloader Boo	
tion declarations	

) Screen

dl306 init(void);

d1306 vfar start (woid) .



- We're going to use the Arduino Uno as ISP programmer to program the ATTiny85 on our PCB, using the header at the back
- Connect the Arduino Uno to the PCB header as shown on next slide (do not connect the Uno through USB yet)
- Double check connections when finished
- Connect Arduino Uno to USB on desktop

Arduino Uno	ATTiny85 Arcade PCB
3V3	VCC
D11	MOSI
D12	MISO
D13	SCK
D10	RESET
GND	GND







- Upload the Arduino ISP code to the Arduino Uno
- First, open the ISP code:

File → Examples → 11. ArduinoISP → ArduinoISP





- Select the correct board:
- Tools → Board (set to Arduino Uno)
- Tools → Port (select correct COM port)
- Tools → Programmer (select AVRISP mkII)
- Upload code to board!



	Auto Format	Ctrl+T			
1	Archive Sketch				
1.	Fix Encoding & Reload				
	Manage Libraries	Ctrl+Shift+I			
13 h+	Serial Monitor	Ctrl+Shift+M			
re	Serial Plotter	Ctrl+Shift+L			
ww	WiFi101 / WiFiNINA Firmware Up	dater			
et	Board: "Arduino Uno"	>	Boards Manager		
i .	Port	>	Arduino AVR Boards		Arduino Yún
	Get Board Info		ATtiny Microcontrollers	٠	Arduino Uno
ul	Programmer: "AV/RISP mkll"	,	ATTinyCore		Arduino Duemilanove or Diecimila
,	Burn Bootloader	1	custom-avr (in sketchbook)		Arduino Nano
IC	, or i notation				Arduino Mega or Mega 2560
					Arduino Mega ADK
	MISO 5V (!) Avoid t	his pin on Due,	Zero		Arduino Leonardo
	SCK MOSI				Arduino Leonardo ETH
	GND				Arduino Micro
Arduinos (Uno,), pins MOSI, MISO and SCK are the same pins as				Arduino Esplora	
pin	11, 12 and 13, respectivel	y. That is why m	any tutorials instruct		Arduino Mini
hook up the target to these pins. If you find this wiring more					Arduino Ethernet
al,	have a define USE_OLD_STYLE	_WIRING. This wi	ll work even when not		Arduino Fio
an Uno. (On an Uno this is not needed).					Arduino BT
-timly you are not able divided with he confirming					LilyPad Arduino USB
atively you can use any other digital pin by configuring re ('BitBanged') SPI and having appropriate defines for PIN_MOSI, SO and PIN SCK.					LilyPad Arduino
					Arduino Pro or Pro Mini
	_				Arduino NG or older
NT:	When using an Arduino that	is not 5V tolera	nt (Due, Zero,) as		Arduino Robot Control
ogrammer, make sure to not expose any of the programmer's pins to 5V. Le way to accomplish this is to power the complete system (programmer					Arduino Robot Motor
					Arduino Gemma
get)	at 3V3.				Adafruit Circuit Playground
	(with register) on the fell	owing pipe.			Arduino Yún Mini
TED	(wron resiscor) on the loli	ie rupping			Arduino Industrial 101
LED tbea	t - shows the programmer	15 19101199			
LED :bea :	<ul> <li>t - shows the programmer</li> <li>- Lights up if somethin</li> </ul>	g goes wrong (us	e red if that makes sense		Linino One



- We can now use the Arduino Uno as ISP to program our ATTiny85 PCB
- First, we need to burn the bootloader (which sets the fuses)



• Under *Tools*, make sure to select the following options:

Board: "ATTiny25/45/85"

Processor: "ATTiny85"

Clock: 16 MHz internal -> EXTREMELY IMPORTANT





- Make sure to change *Tools* **→** *Programmer* to *Arduino* as *ISP*
- Click on Tools → Burn bootloader
- You should get: "Done burning bootloader" if everything went fine (and some beep noises <sup>(i)</sup>), otherwise check connections again



Done burning bootloader.



- We can now program the ATTiny85 from the Arduino IDE
- First, we run a simple hardware test program
- This runs the following sequence:
  - Initialize ports of ATTiny85
  - Initialize OLED screen
  - Shows EAVISE logo (2 seconds)
  - Plays sound
  - Shows test screen to test D-pad and action button







- This sketch is found under "/software/hw\_test/"
- Open in Arduino IDE, make sure that *ATTiny85* board is still selected with 16 MHz clock, and the programmer is *Arduino as ISP*
- Upload the code and test the hardware!



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Hardware

Software


# SW intro (OLED, I2C, ACD, Interrupts)

- Let's now discuss the software side:
  - The OLED screen interfacing
    - I2C interface protocol
  - User input
    - ADCs
    - Interrupts (optional)



- OLED screen specs:
  - SSD1306 controller
  - Supports I2C & SPI
  - 128 x 64 pixels
  - 0.96-inch diagonal
  - Supply voltage 3.3V 5V





- OLED technology:
  - Similar to LED, emissive electroluminescent layer is a film of organic compound that emits light in response to an electric current
  - PMOLED and AMOLED



https://www.unisystem-displays.com/en/news/all-about-oleds.html



- OLED technology:
  - Each pixel emits visible light (as opposed to an LCD screen)
- Advantages:
  - Excellent brightness and contrast
  - Wide viewing-angle
  - No need for backlight: smaller, lightweight, flexible, uses less power
  - Fast response time
- Disadvantages:
  - Expensive technology
  - Limited lifetime of organic material
  - Prone to environmental factors (e.g. moisture)







https://www.unisystem-displays.com/en/news/all-about-oleds.html



- Our screen uses I2C for communication with the SSD1306 controller:
  - Inter-Integrated circuit bus
  - Two wire interface: SCK & SDA: bidirectional and open-collector or open-drain (pull-up required)



Texas Instruments - Application Report SLVA704–June 2015 Understanding the I2C Bus



- I2C
  - Controller (master) communicates with slave devices
  - Slave may not transmit data unless addressed
  - Each device on the I2C bus has a specific address
  - Many slave devices require configuration upon startup to set behavior
  - Typically done through the slave's internal register maps
  - A device can have one or multiple registers where data is stored, written or read







Texas Instruments - Application Report SLVA704–June 2015 Understanding the I2C Bus



\_ A ¦

47

• I2C message



Master Controls SDA Line

Slave Controls SDA Line

#### Write to One Register in a Device



Texas Instruments - Application Report SLVA704–June 2015 Understanding the I2C Bus



• OLED screen - SSD1306 implementation: datasheet p. 20



- Now we know how to send data
- What should we send to do what?  $\rightarrow$  Command table (p. 28 32)
  - (D/C#=0, R/W#(WR#) = 0, E(RD#=1) unless specific setting is stated) 1. Fundamental Command Table D/C#Hex D7 D6 D5 D4 D3 D2 D1 D0 Command Description 0 Set Contrast Control Double byte command to select 1 out of 256 81 1 0 0 0 0 0 1 A[7:0] A<sub>7</sub> A6 contrast steps. Contrast increases as the value 0  $A_5$  $A_4$  $A_3$  $A_2$  $A_1$  $A_0$ increases. (RESET = 7Fh)A4/A5 1 0 X<sub>0</sub> Entire Display ON A4h, X0=0b: Resume to RAM content display 1 0 0 1 0 (RESET) Output follows RAM content A5h, X<sub>0</sub>=1b: Entire display ON Output ignores RAM content A6h, X[0]=0b: Normal display (RESET) A6/A7 1 0 1 0 0 1 1 X<sub>0</sub> Set Normal/Inverse 0 in RAM: OFF in display panel Display 1 in RAM: ON in display panel A7h, X[0]=1b: Inverse display 0 in RAM: ON in display panel 1 in RAM: OFF in display panel X<sub>0</sub> Set Display ON/OFF AEh, X[0]=0b:Display OFF (sleep mode) AE 0 1 0 1 1 1 (RESET) AF AFh X[0]=1b:Display ON in normal mode

#### 9 COMMAND TABLE

#### Table 9-1: Command Table

• Different types: fundamental, scrolling, addressing, HW configuration, timing



• How does the screen work?

		Row re-mapping
PAGE0 (COM0-COM7)	Page 0	PAGE0 (COM 63-COM56)
PAGE1 (COM8-COM15)	Page 1	PAGE1 (COM 55-COM48)
PAGE2 (COM16-COM23)	Page 2	PAGE2 (COM47-COM40)
PAGE3 (COM24-COM31)	Page 3	PAGE3 (COM39-COM32)
PAGE4 (COM32-COM39)	Page 4	PAGE4 (COM31-COM24)
PAGE5 (COM40-COM47)	Page 5	PAGE5 (COM23-COM16)
PAGE6 (COM48-COM55)	Page 6	PAGE6 (COM15-COM8)
PAGE7 (COM56-COM63)	Page 7	PAGE7 (COM 7-COM0)
	SEG0SEG127	
Column re-mapping	SEG127SEG0	





• Set address pointer for GDDRAM

	3. Addressing Setting Command Table											
]	D/C#Hex	<b>D</b> 7	D6	D5	D4	D3	D2	D1	D0	Command	Description	
0	00~0F	0	0	0	0	X3	$X_2$	X <sub>1</sub>	$X_0$	Set Lower Column	Set the lower nibble of the column start address	
										Start Address for	register for Page Addressing Mode using X[3:0]	
										Page Addressing	as data bits. The initial display line register is	
										Mode	reset to 00000 after RESET.	
											Note	
											<sup>(1)</sup> This command is only for page addressing mode	
0	) 10~1F	0	0	0	1	$X_3$	$X_2$	X <sub>1</sub>	$X_0$	Set Higher Column	Set the higher nibble of the column start address	
										Start Address for	register for Page Addressing Mode using X[3:0]	
										Page Addressing	as data bits. The initial display line register is	
										Widde	reset to 00000 after KESE1.	
											Note	
											<sup>(1)</sup> This command is only for page addressing mode	
0	) B0~B		0	1	1	0	$X_2$	$X_1$	X <sub>0</sub>	Set Page Start	Set GDDRAM Page Start Address	
										Addressing Mode	(PAGE0~PAGE7) for Page Addressing Mode	
										rourcosing mode	come vita.ol.	
											Note	
											<sup>(1)</sup> This command is only for page addressing mode	



• Startup sequence



Figure 2 : Software Initialization Flow Chart



- Let's have a look how this is programmed in our Arduino IDE
- Task 6:
  - Open "oled\_driver.ino" in Arduino IDE
  - Examine code, try to understand how it works
  - Use the loop function to:
    - 1. Initialize the screen
    - 2. Clear the screen
    - 3. Draw a one-pixel border around the screen
    - 4. Write your name in the middle of the screen, using: void ssd1306\_char\_f6x8(uint8\_t x, uint8\_t y, const char ch[])
    - 5. Optional: move or scroll it across the screen? Experiment yourself!



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Hardware

Software



- Now we are going to read the user input buttons
- How many user IOs are there? How many pins on microcontroller?
- Schematic:







• We use a trick to reduce the required IO ports

**1** kΩ

Often used in hardware design

P3 220 Ω P2 220 Ω P1 220 Ω P0 220 Ω P0 220 Ω P1 220 Ω

**1** kΩ











- We use different analog values through voltage dividers on the analog inputs of the ATTiny85
  - ADCs to determine button press!
- How do they work on the ATTiny85?
  - 4 channels, single 10-bit ADC
  - Successive approximation









Successive Approximation – example of a 4-bit ADC









- A lot of settings!
  - MUX, reference voltage, enables, pre-scaler, interrupts, how 10-bit is stored in 8-bit registers, mode of operation,...
  - 5 registers!
- Luckily, Arduino libraries perform lots of abstraction:
  - analogReadResolution(10) ;
  - analogReference(DEFAULT);
    - analogRead(A0);



- Task 7:
  - Calculate the expected ADC values for each of the 4 buttons (up, down, left, right)
  - Open "user\_input.ino" in Arduino IDE
  - Examine code, try to understand how it works
  - Extend the code to:
    - 1. Initialize the user IOs
    - Show the ADC values on the OLED screen tip: itoa(); to convert int to char
    - 3. Show which buttons were pressed





- Reading buttons this way is not efficient
  - Sometimes OK, when SW routine is very predictable (e.g. game console)
- Interrupt the running code to do something else
- (Very) short routines (no delays)!
- Internal or external
- Examples: timer, watchdog, keyboard, sensor, switch





- ACTION button is on PCINT0 pin
- Two types in ATTiny85



- INT0 triggers a direct dedicated interrupt routine
  - Rising or falling is set through register
- PCINT (**Pin Change INTerrupt**) triggers an interrupt routine if one of the PCINT pins are triggered. You have to check which pin and what change yourself in the interrupt routine

Table 9-1. Reset and Interrupt Vectors									
Vector No.	Program Address	Source	Interrupt Definition						
1	0x0000	RESET	External Pin, Power-on Reset, Brown-out Reset, Watchdog Reset						
2	0x0001	INT0	External Interrupt Request 0						
3	0x0002	PCINT0	Pin Change Interrupt Request 0						
4	0x0003	TIMER1_COMPA	Timer/Counter1 Compare Match A						
5	0x0004	TIMER1_OVF	Timer/Counter1 Overflow						
6	0x0005	TIMER0_OVF	Timer/Counter0 Overflow						



• INTO

Bit	7	6	5	4	3	2	1	0	_
0x3B	-	INT0	PCIE	-	-	-	-	-	GIMSK
Read/Write	R	R/W	R/W	R	R	R	R	R	•
Initial Value	0	0	0	0	0	0	0	0	
	7	6	5	4	3	2	1	0	_
	BODS	PUD	SE	SM1	SM0	BODSE	ISC01	ISC00	MCUCR
	R	R/W	R/W	R/W	R/W	R	R/W	R/W	-
	0	0	0	0	0	0	0	0	

ISC01	ISC00	Description
0	0	The low level of INT0 generates an interrupt request.
0	1	Any logical change on INT0 generates an interrupt request.
1	0	The falling edge of INT0 generates an interrupt request.
1	1	The rising edge of INT0 generates an interrupt request.

attachInterrupt(digitalPinToInterrupt(PIN\_NUMBER), routine, RISING);

void routine() {

}

YOUR CODE HERE

Note: not supported by all ATTiny-cores



#### PCINT0\_vect

Bit	7	6	5	4	3	2	1	0	
0x15	-	-	PCINT5	PCINT4	PCINT3	PCINT2	PCINT1	PCINT0	PCMSK
Read/Write	R	R	R/W	R/W	R/W	R/W	R/W	R/W	•
Initial Value	0	0	0	0	0	0	0	0	

Bits 5:0 – PCINT[5:0]: Pin Change Enable Mask 5:0

Each PCINT[5:0] bit selects whether pin change interrupt is enabled on the corresponding I/O pin.

Bit	7	6	5	4	3	2	1	0	_
0x3B	-	INT0	PCIE	-	-	-	-	-	GIMSK
Read/Write	R	R/W	R/W	R	R	R	R	R	-
Initial Value	0	0	0	0	0	0	0	0	

Set registers yourself in setup() of Arduino code!

PCMSK |= bit (PCINT0); GIMSK |= 0b00100000; ISR(PCINT0\_vect) {

YOUR CODE HERE (check which pin and change)



• Finally, enable all interrupts



#### • Bit 7 - I: Global Interrupt Enable

The Global Interrupt Enable bit must be set for the interrupts to be enabled. The individual interrupt enable control is then performed in separate control registers. If the Global Interrupt Enable Register is cleared, none of the interrupts are enabled independent of the individual interrupt enable settings. The I-bit is cleared by hardware after an interrupt has occurred, and is set by the RETI instruction to enable subsequent interrupts. The I-bit can also be set and cleared by the application with the SEI and CLI instructions, as described in the instruction set reference.

- sei(); or interrupts();
- cli(); or noInterrupts();



- Let's have a look how this is programmed in our Arduino IDE
- Task 8 optional:
  - Extend "user\_input.ino" with interrupt routine for the ACTION button
    - Uncomment the previous code for ACTION button read



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# Develop simple Snake game

- Final task 9:
  - program a simple game: Snake



- Rules:
  - Snake moves in one of four directions at each new timeframe
  - Direction controlled by D-pad
  - Bait randomly positioned on screen
  - If bait is catched, length of the snake, score and speed increases
  - At borders, snake reappears at the opposite side of the game grid
  - · Game over when snake collides with itself





**KU LEUVEN** 

**G**PA'

# Develop simple Snake game

- How to start?
  - → Develop flowchart of game
- This has already been done for you! Let's have a look.



### Develop simple Snake game

- A skeleton code framework has already been developed for you
- You need to write specific functions
  - Some are optional
- Let's look at the Arduino code
- Download the skeleton code and run
  - Generates startup
  - · Gives heartbeat and draws border







# Develop simple Snake game

- *Render\_game()* explanation
  - Game grid is 16 x 32
    - Stored in unsigned long screenBuffer[16];
    - = 4 bytes = 32 bits
  - Screen is 64 x 128

Each game pixel is a 4 x 4 pixel on the OLED screen




- Render\_game() converts the screenBuffer[16] variable to OLED pixels
- You only need do two things:
  - Set a '1' at each position in the screenBuffer for each segment of the snake and the single bait
  - Indicate the position of the bait with two variables
    - int baitX
    - int baitY
  - Note: allowed snake and bait positions are X: 0-31 and Y: 0-15



- Let's try this:
  - Uncomment draw\_snake() and upload
- Now it's up to you!
- Task 9 begins: you are now going to implement the missing functions yourself
  - One by one: upload after each (partly) adjusted function
  - We'll walk you through each function (don't worry <sup>(C)</sup>)

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- First, define a global variable to hold the current direction
  - Byte: 0: up, 1: left, 2: down, 3: right
  - Don't forget to reset this variable in resetGame();
- Function checks if U/D/L/R was pressed, and changes the direction if needed
  - Move in opposite direction not allowed!
- To test, print the current direction as text on the screen
- Upload to test if it works! 
   any remaining issues?









- Move each segment of the snake in the right direction
- Use variables xPos[], yPos[] and len
- Tip: use case-statement since direction is unambiguous
- Don't forget the borders of the screen!
- Note: valid xPos = 0 31, valid yPos = 0 15
- Upload! The snake should now move over the game grid







- Generate random positions for a new bait (preferably not on the edges)
  - baitX: 1 30, baitY: 1 14
- Test if bait is not dropped on snake itself!
- Print baitX and baitY somewhere on the screen as test for now









- · See if the snake catched the bait with its head
- Return Boolean true or false
- Increment score and len in this function
- Don't forget to limit the *len* to *maxLen*
- You can play a sound if the bait is catched playMusic(BaitMusic, 4);
- Do not upload yet, first fix next function







- Draw the bait in the screen buffer
- Set a '1' at the correct location in the buffer
- Remember: render\_game() knows the difference between bait and snake based on baitX and baitY
- Use function *draw\_snake()* as example
- Extremely short function
- Upload and test! You should be able to play the game (without collision detection)







- See if the head of the snake collided with a segment of itself
- Return Boolean true or false



- That's it! The game is finished. Well done.
- We have some optional functions left (simple intermediate advanced expert):



• Simple! Draw the current score each frame in one of the corners of the screen







- Intermediate!
- At startup of the game see if e.g. UP was held pressed for specific time (e.g. 2 seconds)
- Mute or unmute sound if this was the case
  - Through global variable
  - Use as condition in *beep*-function
- Display mute or sound on top of the screen at startup







- Advanced! Use EEPROM to store previous high score
- After game over, load the high score from EEPROM
- Compare with current score

If higher, display on screen and write new high score to EEPROM

• Tips: EEPROM.read(), EEPROM.write() EEPROM is read/written per byte. Int is 2 bytes long







- Expert!
- After game over, put ATTiny85 in sleep mode
- Wake up after interrupt (PCINT0)
- Steps: clear and switch off OLED screen, switch ADC off, then enable sleep mode and sleep. On power up from sleep switch ADC and OLED screen back on



# • -

- Develop your own variations!
  - Game over when you go out of the screen?
  - You could for example use the ACTION button to let the snake jump over itself!

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### Download finished games

• Feel free to download any of the following finished games, found in the finished\_games folder:

#### <u>Q\*bert (1982)</u>



#### Arkanoid (1986)



#### Excite Bike (1984)



#### Bomberman (1983)



#### Dugger (1988)



#### Frogger (1981)



#### Space Invaders (1978)



#### Tiny Gilbert (platformer)





### Introduction





• Feel free to download any of the following finished games, found in the finished\_games folder:

#### Morpion (tic-tac-toe)



#### Pacman (1980)



<u> Pinball (1984)</u>



#### Pipeline (1978)



#### Plaque Attack (1983)



#### Hat Trick (1988)



#### <u>Tetris (1984)</u>



#### Missile Command (1980)





## Download finished games

- A few online sources for other games:
  - <u>https://github.com/andyhighnumber/Attiny-Arduino-Games</u>
  - <u>https://github.com/webboggles/AttinyArcade</u>
  - <u>https://www.tinyjoypad.com/tinyjoypad\_attiny85</u>
  - <u>https://www.tinyjoypad.com/arduboy</u>

➔ Some require code modification or additional libraries (e.g. different pins for OLED, coded for fewer buttons, etc.)



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### The end

• We hope you enjoyed this workshop!

